

Optimal Portfolio Under Worst-Case Scenarios

**Carole Bernard (UW), Jit Seng Chen (UW)
and Steven Vanduffel (Vrije Universiteit Brussel)**



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Contributions

- 1 A better understanding of the link between Growth Optimal Portfolio and optimal investment strategies
- 2 Understanding issues with traditional diversification strategies and how **lowest outcomes of optimal strategies always happen in the worse states of the economy.**
- 3 Develop **innovative** strategies to cope with this observation.
- 4 Implications in terms of **assessing the risk and return** of a strategy and in terms of **reducing systemic risk**

Part I:

Traditional

Diversification Strategies

Growth Optimal Portfolio (GOP)

- The **Growth Optimal Portfolio** (GOP) maximizes expected logarithmic utility from terminal wealth.
- It has the property that it **almost surely accumulates more wealth than any other strictly positive portfolios after a sufficiently long time**.
- Under general assumptions on the market, the GOP is a diversified portfolio.
- Details in Platen (2006).

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For example, in the Black-Scholes model

- A Black-Scholes financial market (mainly for ease of exposition)
- Risk-free asset $\{B_t = B_0 e^{rt}, t \geq 0\}$
-

$$\begin{cases} \frac{dS_t^1}{S_t^1} = \mu_1 dt + \sigma_1 dW_t^1 \\ \frac{dS_t^2}{S_t^2} = \mu_2 dt + \sigma_2 dW_t^2 \end{cases}, \quad (1)$$

where W^1 and W are two correlated Brownian motions under the physical probability measure \mathbb{P} .

$$W_t = \rho W_t^1 + \sqrt{1 - \rho^2} W_t^2$$

where W^1 and W^2 are independent.

Constant-Mix Strategy

- Dynamic rebalancing to preserve the initial target allocation
- The payoff of a constant-mix strategy is

$$S_t^\pi = S_0^\pi \exp(X_t^\pi)$$

where X_t^π is normal.

- For an initial investment V_0 , V_T is given by

$$V_T = V_0 \frac{S_T^\pi}{S_0^\pi},$$

where π is the vector of proportions.

Growth Optimal Portfolio (GOP)

In the 2-dimensional Black-Scholes setting,

- The GOP is a constant-mix strategy with $X_t^\pi = \left(\mu_\pi - \frac{1}{2}\sigma_\pi^2\right) t + \sigma_\pi W_t^\pi$, that **maximizes the expected growth rate** $\mu_\pi - \frac{1}{2}\sigma_\pi^2$. It is

$$\pi^\star = \Sigma^{-1} \cdot (\mu - r\mathbf{1}). \quad (2)$$

- constant-mix portfolios** given by $\pi = \alpha\pi^\star$ with $\alpha > 0$ and where π^\star is the optimal proportion for the GOP, are optimal strategies for CRRA expected utility maximizers. With a constant relative risk aversion coefficient $\eta > 0$, CRRA utility is

$$U(x) = \begin{cases} \frac{x^{1-\eta}}{1-\eta} & \text{when } \eta \neq 1 \\ \log(x) & \text{when } \eta = 1, \end{cases}$$

and $\alpha = 1/\eta$.

Market Crisis

The **growth optimal portfolio** S^* can also be interpreted as a major market index. Hence it is intuitive to define a stressed market (or crisis) at time T as an event where *the market* - materialized through S^* - **drops below its Value-at-Risk** at some high confidence level. The corresponding states of the economy verify

$$\text{Crisis states} = \{S_T^* < q_\alpha\}, \quad (3)$$

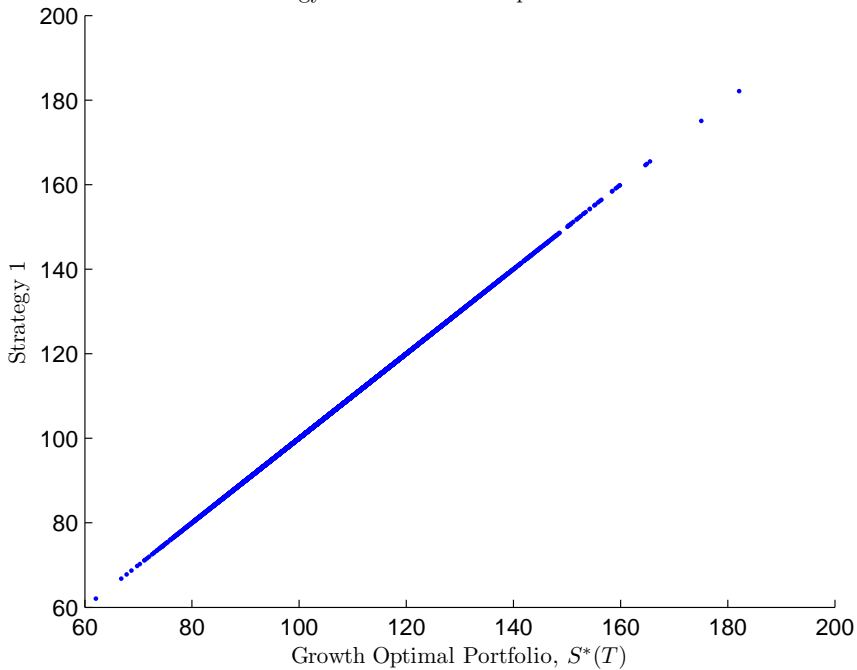
where q_α is such that $P(S_T^* < q_\alpha) = 1 - \alpha$ and α is typically high (e.g. $\alpha = 0.98$).

Strategy 1: GOP

We invest fully in the GOP.

In a crisis (GOP is low), our portfolio is low!

Strategy 1 vs the Growth Optimal Portfolio



Strategy 2: Buy-and-Hold

The buy-and-hold strategy is the simplest investment strategy. An initial amount V_0 is used to purchase w_0 units of the bank account and w_i units of stock S^i ($i = 1, 2$) such that

$$V_0 = w_0 + w_1 S_0^1 + w_2 S_0^2,$$

and no further action is undertaken.

Example with $1/3$ invested in each asset (bank, S_1 and S_2) on next slide.

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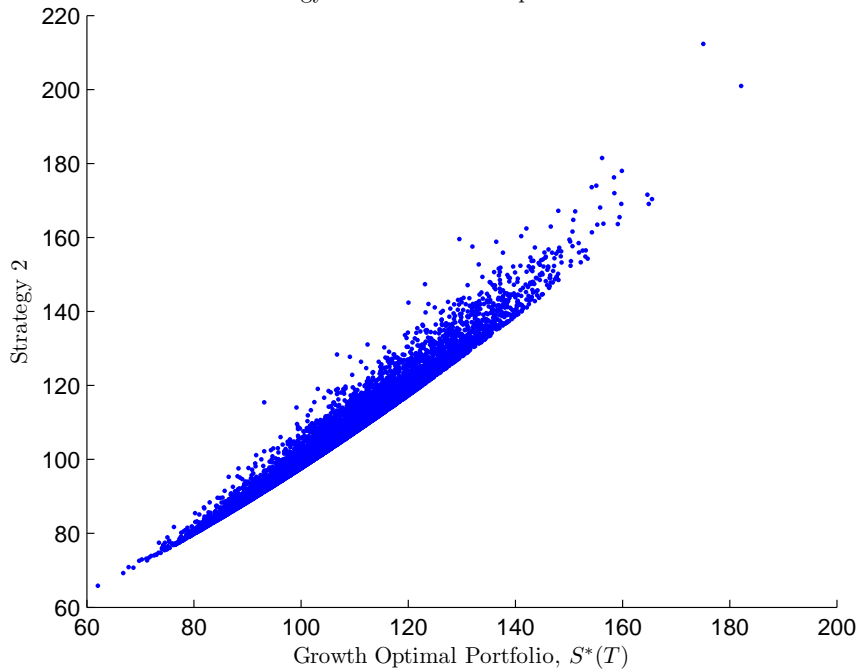
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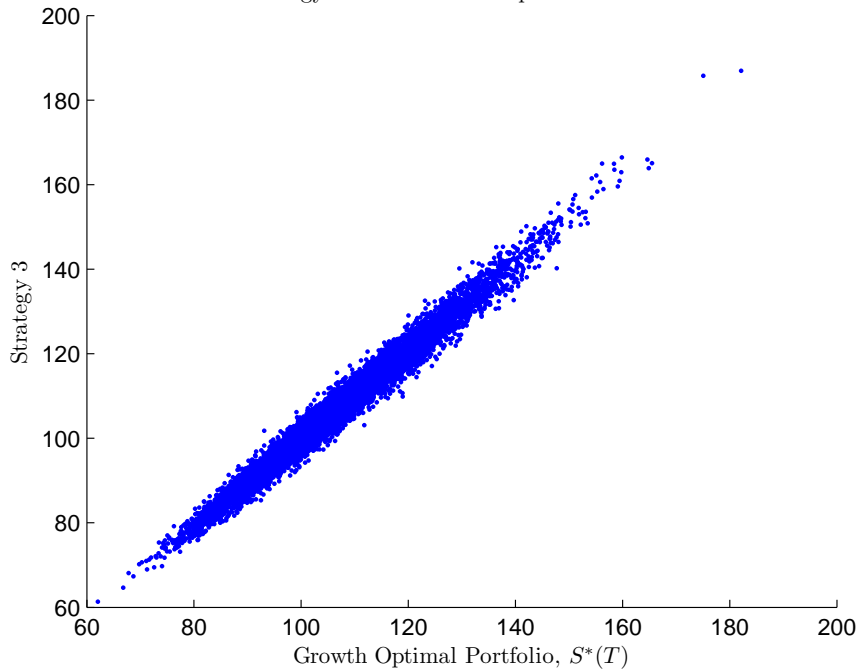
Strategy 2 vs the Growth Optimal Portfolio



Strategy 3: Constant-Mix Strategy

Example with $1/3$ invested in each asset (bank, S_1 and S_2).

Strategy 3 vs the Growth Optimal Portfolio



- ▶ These three traditional diversification strategies do not offer protection during a crisis.
- ▶ In a more general setting, optimal strategies share the same problem...

Part II:

Optimal portfolio selection for law-invariant preferences

Stochastic Discount Factor and Real-World Pricing:

The GOP can be used as numeraire to price under P

$$\left\{ \begin{array}{l} \text{Price of} \\ X_T \text{ at } 0 \end{array} \right\} = E_Q[e^{-rT} X_T] = E_P[\xi_T X_T] = E_P \left[\frac{X_T}{S_T^*} \right]$$

where $S_0^* = 1$.

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Cost-efficient strategies (Dybvig (1988))

Optimal Portfolio Selection Problem: Consider an investor with fixed investment horizon:

$$\max_{\mathbf{X}_T} \mathcal{U}(\mathbf{X}_T)$$

subject to a given “cost of X_T ” (equal to initial wealth)

- **Law-invariant** preferences $X_T \sim Y_T \Rightarrow \mathcal{U}(X_T) = \mathcal{U}(Y_T)$
- **Increasing** preferences

$$X_T \sim F, Y_T \sim G, \forall x, F(x) \leq G(x) \Rightarrow \mathcal{U}(X_T) \geq \mathcal{U}(Y_T)$$

A strategy (or a payoff) is cost-efficient

if any other strategy that generates the same distribution under P costs at least as much.

The optimal strategy for \mathcal{U} must be **cost-efficient**.

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Optimal Portfolio and Cost-efficiency

Consider an investor with **increasing law-invariant** preferences and a **fixed** horizon. Denote by X_T the investor's final wealth. The optimal strategy solves a cost-efficiency problem

$$\min_{\{X_T \mid X_T \sim F\}} \mathbb{E} \left[\frac{X_T}{S_T^*} \right]$$

Reciprocally a cost-efficient strategy with a continuous distribution F corresponds to the optimum of an expected utility investor for

$$U(x) = \int_0^x G^{-1}(1 - F(y)) dy$$

where G is the cdf of $\frac{1}{S_T^*}$.

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Black-Scholes Model

Theorem

Consider the following optimization problem:

$$PD(F) := \min_{\{X_T \mid X_T \sim F\}} \mathbb{E} \left[\frac{X_T}{S_T^*} \right]$$

In a Black-Scholes model, the optimal strategy (cheapest way to get F) is

$$X_T^* = F^{-1} \left(F_{S_T^*}(S_T^*) \right).$$

Note that $X_T^ \sim F$ and X_T^* is a.s. **unique**.*

Corollary

A strategy with payoff $X_T = h(S_T^)$ is cost-efficient if and only if h is non-decreasing.*

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Idea of the proof

$$\begin{array}{ll} \min_{X_T} & \mathbb{E} \left[\frac{X_T}{S_T^*} \right] \\ \text{subject to} & \begin{cases} X_T \sim F \\ \frac{1}{S_T^*} \sim G \end{cases} \end{array}$$

Recall that

$$\text{corr} \left(X_T, \frac{1}{S_T^*} \right) = \frac{\mathbb{E} \left[X_T \frac{1}{S_T^*} \right] - \mathbb{E} \left[\frac{1}{S_T^*} \right] \mathbb{E} [X_T]}{\text{std} \left(\frac{1}{S_T^*} \right) \text{std} (X_T)}.$$

We can prove that when the distributions for both X_T and $\frac{1}{S_T^*}$ are fixed, we have

$$(\mathbf{X}_T, \mathbf{S}_T^*) \text{ is comonotonic} \Rightarrow \text{corr} \left[\mathbf{X}_T, \frac{1}{\mathbf{S}_T^*} \right] \text{ is minimal.}$$

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Part III:

Investment under

Worst-Case Scenarios

Investment with State-Dependent Constraints

Problem considered so far

$$\min_{\{X_T \mid X_T \sim F\}} \mathbb{E} \left[\frac{X_T}{S_T^*} \right].$$

A payoff that solves this problem is **cost-efficient**.

New Problem

$$\min_{\{V_T \mid V_T \sim F, \mathbb{S}\}} \mathbb{E} \left[\frac{V_T}{S_T^*} \right].$$

where \mathbb{S} denotes a set of constraints. A payoff that solves this problem is called a **\mathbb{S} -constrained cost-efficient payoff**.

Type of Constraints

We are able to find optimal strategies with final payoff V_T

- ▶ with an additional probability constraint

$$P(S_T^* \leq s, V_T \leq v) = \beta$$

- ▶ with a set of probability constraints

$$\forall (s, v) \in \mathbb{S}, P(S_T^* \leq s, V_T \leq v) = Q(s, v)$$

where Q is an appropriate given function and \mathbb{S} verifies some properties.

- ▶ in particular, assuming that the final payoff of the strategy is independent of S_T^* during a crisis (defined as $S_T^* \leq q_\alpha$),

$$\forall s \leq q_\alpha, v \in \mathbb{R}, P(S_T^* \leq s, V_T \leq v) = P(S_T^* \leq s)P(V_T \leq v)$$

Independence in the Tail - Strategy 4: Path-dependent

Theorem

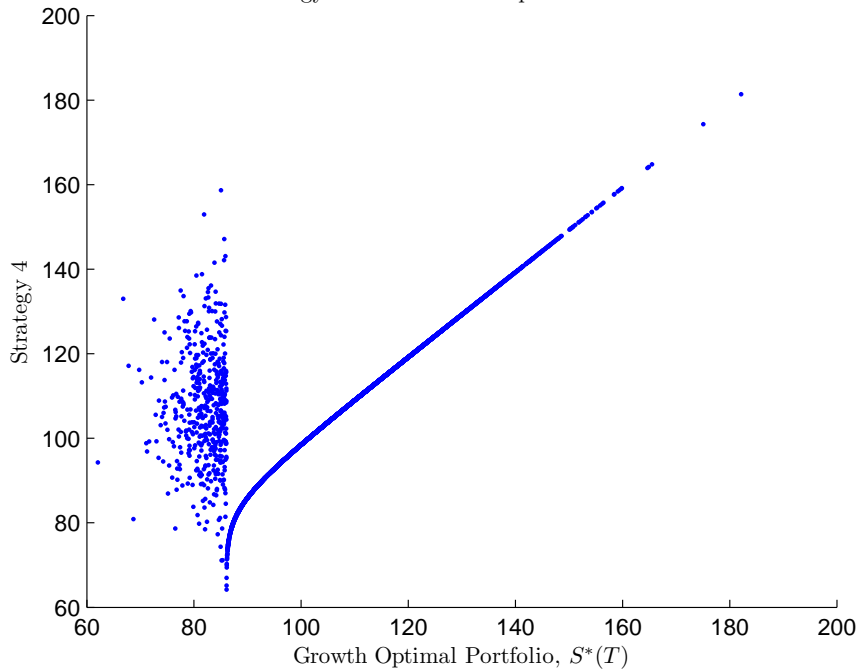
The cheapest path-dependent strategy with a cumulative distribution F but such that it is independent of S_T^ when $S_T^* \leq q_\alpha$ can be constructed as*

$$V_T^* = \begin{cases} F^{-1} \left(\frac{F_{S_T^*}(S_T^*) - \alpha}{1 - \alpha} \right) & \text{when } S_T^* > q_\alpha, \\ F^{-1} \left(\Phi \left(\frac{\ln \left(\frac{S_t^*}{(S_T^*)^{t/T}} \right) - (1 - \frac{t}{T}) \ln(S_0^*)}{\sigma_* \sqrt{t - \frac{t^2}{T}}} \right) \right) & \text{when } S_T^* \leq q_\alpha, \end{cases} \quad (4)$$

where $t \in (0, T)$ can be chosen freely.

(No uniqueness and path-independence anymore).

Strategy 4 vs the Growth Optimal Portfolio



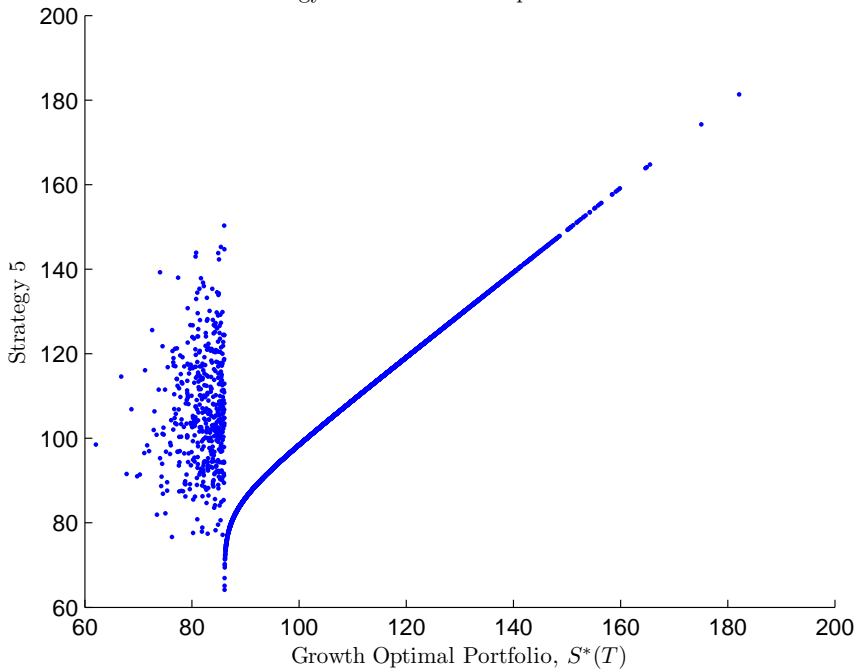
Independence in the Tail - Strategy 5: Path-independent

In a financial market that **contains at least two assets** that are continuously distributed, the **cheapest** path-independent strategy with a cumulative distribution F but such that it is **independent** of S_T^* when $S_T^* \leq q_\alpha$ can be constructed as

$$Z_T^* = \begin{cases} F^{-1} \left(\frac{F_{S_T^*}(S_T^*) - \alpha}{1 - \alpha} \right) & \text{when } S_T^* > q_\alpha \\ F^{-1}(\Phi(A)) & \text{when } S_T^* \leq q_\alpha \end{cases} . \quad (5)$$

where A is explicitly known as a function of S_T^1 and S_T^* .

Strategy 5 vs the Growth Optimal Portfolio



Part IV:

Investment under

Worst-Case Scenarios

Some numerical examples

Other Types of Dependence

Recall that the joint cdf of a couple (S_T^*, X) writes as

$$P(S_T^* \leq s, X_T \leq x) = C(H(s), F(x))$$

where

- The marginal cdf of S_T^* : H
- The marginal cdf of X_T : F
- A copula C

Independence in the tail (independence copula $C(u, v) = uv$):

$$\forall s \leq q_\alpha, v \in \mathbb{R}, P(S_T^* \leq s, V_T \leq v) = P(S_T^* \leq s)P(V_T \leq v)$$

- ▶ We were also able to derive formulas for optimal strategies that generate a **Gaussian distribution** in the tail with a correlation coefficient of -0.5.
- ▶ Similarly for **Clayton** or **Frank** dependence.

Optimal Investment with a Clayton Tail Dependence

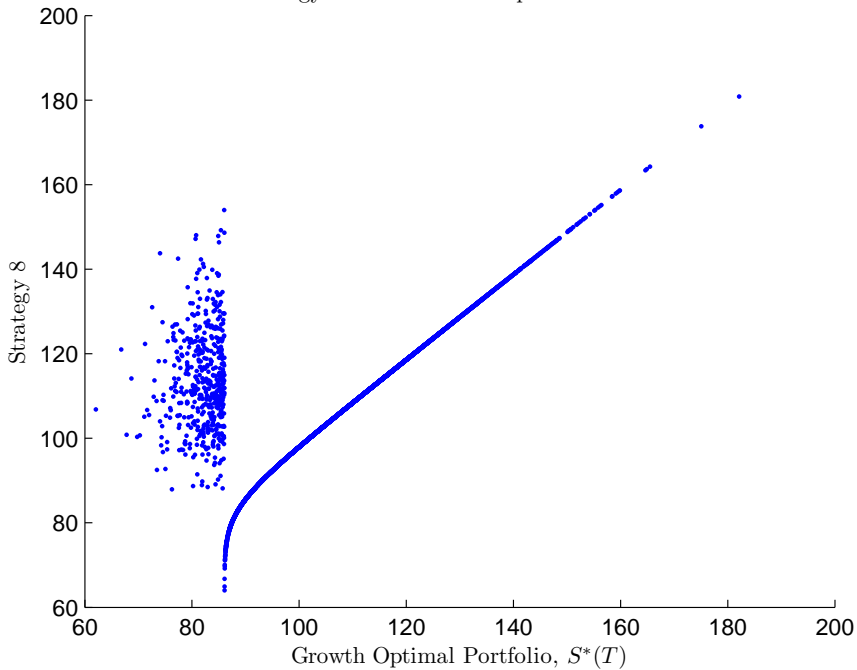
The **cheapest** strategy V_T^* with cdf F that verifies this **Clayton** dependence (with correlation -0.5) in the tail is

$$V_T^* = \begin{cases} F^{-1} \left(\left[(F_{S_T^*}(S_T^*) - \alpha)^{-a} - (1 - \alpha)^{-a} + 1 \right]^{-1/a} \right) & \text{if } S_T^* > q_\alpha \\ F^{-1} \left(g \left(1 - F_{S_T^*}(S_T^*), j_{F_{S_T^*}(S_T^*)}(F_{Z_T}(Z_T)) \right) \right) & \text{if } S_T^* \leq q_\alpha \end{cases}$$

where Z_T is such that (S_T^*, Z_T) is continuously distributed (with copula J) and where g is known explicitly:

$$g(u, v) = \left[u^{-a} \left(v^{-a/(1+a)} - 1 \right) + 1 \right]^{-1/a}.$$

Strategy 8 vs the Growth Optimal Portfolio



Some numerical results

We define two events related to *the market*, i.e. the market **crisis**

$\mathbf{C} = \{\mathbf{S}_T^* < \mathbf{q}_\alpha\}$ and a **decrease** in the market

$\mathbf{D} = \{\mathbf{S}_T^* < \mathbf{S}_0^* e^{rT}\}$. We further define two events for the portfolio value by $A = \{V_T < V_0 e^{rT}\}$ and $B = \{V_T < 75\% V_0 e^{rT}\}$

	T	Cost	Sharpe	$P(A \mathbf{C})$	$P(A \mathbf{D})$	$P(B \mathbf{C})$
GOP	5	100	0.266	1.00	1.00	1.00
Buy-and-Hold	5	100	0.239	0.9998	0.965	0.99
Independence	5	101.67	0.214	0.46	0.94	0.13
Gaussian	5	103.40	0.159	0.12	0.90	0.01
Clayton	5	102.35	0.193	0.24	0.91	0.02

Conclusions

- **Cost-efficiency:** a preference-free framework for ranking different investment strategies.
- **Characterization of optimal portfolio strategies** for investors with law invariant preferences and a fixed horizon.
- ▶ **Lowest outcomes in worst states** of the economy
- Optimal investment choice under **state-dependent** constraints.
 - not always non-decreasing with the GOP S_T^* .
 - not anymore unique
 - could be path-dependent.
- ▶ **Trade-off** between losing “utility” and gaining from better fit of the investor’s preferences.

More Implications

- ▶ The new strategies do not incur their biggest losses in the worst states in the economy.
- ▶ can be used to **reduce systemic risk**.
 - the idea of assessing risk and performance of a portfolio not only by looking at its final distribution but also by looking at its interaction with the economic conditions is indeed related to the increasing concern to evaluate systemic risk.
 - Acharya (2009) explains that regulators should “be regulating each bank as a function of both its joint (correlated) risk with other banks as well as its individual (bank-specific) risk”.
 - An insight of this work is that if all institutional investors implement strategies that are resilient against crisis regimes, as we propose, then systemic risk can be diminished.

Do not hesitate to contact me to get updated working papers!

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Part V:

Proofs with Copulas

Optimal Portfolio under Tail Dependence

Copulas and Sklar's theorem

The joint cdf of a couple (ξ_T, X) can be decomposed into 3 elements

- The marginal cdf of ξ_T : G
- The marginal cdf of X_T : F
- A copula C

such that

$$P(\xi_T \leq \xi, X_T \leq x) = C(G(\xi), F(x))$$

Where do copulas appear?

in the derivation of “cost-efficient” strategies...

Solving the cost-efficiency problem amounts to finding bounds on copulas!

$$\begin{array}{ll} \min_{X_T} & \mathbb{E}[\xi_T X_T] \\ \text{subject to} & \left\{ \begin{array}{l} X_T \sim F \\ \xi_T \sim G \end{array} \right. \end{array}$$

Proof of the cost-efficient payoff

$$\begin{array}{ll} \min_{X_T} & \mathbb{E}[\xi_T X_T] \\ \text{subject to} & \begin{cases} X_T \sim F \\ \xi_T \sim G \end{cases} \end{array}$$

The distribution G is known and depends on the financial market.
Let C denote a copula for (ξ_T, X) .

$$\mathbb{E}[\xi_T X] = \int \int (1 - G(\xi) - F(x) + C(G(\xi), F(x))) dx d\xi, \quad (6)$$

The lower bound for $\mathbb{E}[\xi_T X]$ is derived from the lower bound on C

$$\max(u + v - 1, 0) \leq C(u, v)$$

(where $\max(u + v - 1, 0)$ corresponds to the **anti-monotonic** copula).

$$E[\xi_T F^{-1}(1 - G(\xi_T))] \leq E[\xi_T X_T]$$

then $X_T^* = F^{-1}(1 - G(\xi_T))$ has the **minimum** price for the cdf F .

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then $X_T^* = F^{-1}(1 - G(\xi_T))$ has the minimum price for the cdf F .

Sufficient condition for the existence

Theorem

Let $t \in (0, T)$. If there exists a copula L satisfying \mathbb{S} such that $L \leq C$ (pointwise) for all other copulas C satisfying \mathbb{S} then the payoff Y_T^ given by*

$$Y_T^* = F^{-1}(f(\xi_T, \xi_t))$$

is a \mathbb{S} -constrained cost-efficient payoff. Here $f(\xi_T, \xi_t)$ is given by

$$f(\xi_T, \xi_t) = (\ell_{G(\xi_T)})^{-1} [j_{G(\xi_T)}(G(\xi_t))],$$

where the functions $j_u(v)$ and $\ell_u(v)$ are defined as the first partial derivative for $(u, v) \rightarrow J(u, v)$ and $(u, v) \rightarrow L(u, v)$ respectively and where J denotes the copula for the random pair (ξ_T, ξ_t) .

If (U, V) has a copula L then $\ell_u(v) = \mathbb{P}(V \leq v | U = u)$.

When $\mathbb{S} = \emptyset$, $f(\xi_t, \xi_T) = F^{-1}(1 - G(\xi_T))$.

Sufficient condition for the existence

Theorem

Let $t \in (0, T)$. If there exists a copula L satisfying \mathbb{S} such that $L \leq C$ (pointwise) for all other copulas C satisfying \mathbb{S} then the payoff Y_T^ given by*

$$Y_T^* = F^{-1}(f(\xi_T, \xi_t))$$

is a \mathbb{S} -constrained cost-efficient payoff. Here $f(\xi_T, \xi_t)$ is given by

$$f(\xi_T, \xi_t) = (\ell_{G(\xi_T)})^{-1} [j_{G(\xi_T)}(G(\xi_t))],$$

where the functions $j_u(v)$ and $\ell_u(v)$ are defined as the first partial derivative for $(u, v) \rightarrow J(u, v)$ and $(u, v) \rightarrow L(u, v)$ respectively and where J denotes the copula for the random pair (ξ_T, ξ_t) .

If (U, V) has a copula L then $\ell_u(v) = \mathbb{P}(V \leq v | U = u)$.

When $\mathbb{S} = \emptyset$, $f(\xi_t, \xi_T) = F^{-1}(1 - G(\xi_T))$.

Existence of the optimum \Leftrightarrow Existence of minimum copula

Theorem (Sufficient condition for existence of a minimal copula L)

Let \mathbb{S} be a **rectangle** $[u_1, u_2] \times [v_1, v_2] \subseteq [0, 1]^2$. Then a minimal copula $L(u, v)$ satisfying \mathbb{S} exists and is given by

$$L(u, v) = \max \{0, u + v - 1, K(u, v)\}.$$

where $K(u, v) = \max_{(a,b) \in \mathbb{S}} \{Q(a, b) - (a - u)^+ - (b - v)^+\}.$

Proof in a note written with Xiao Jiang and Steven Vanduffel extending Tankov's result.

Consequently the existence of a \mathbb{S} -constrained cost-efficient payoff is guaranteed when \mathbb{S} is a rectangle. More generally it also holds when $\mathbb{S} \subseteq [0, 1]^2$ satisfies a “monotonicity property” of the upper and lower “boundaries” and

$$\forall (u, v_0), (u, v_1) \in \mathcal{S}, \quad \left(u, \frac{v_0 + v_1}{2}\right) \in \mathcal{S}. \quad (7)$$